IMPROVED BINARY DITHER-MODULATION WITH PERCEPTUAL CONSTRAINTS

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ABSTRACT

The binary Distortion Compensated Dither-Modulation (DC-DM), which can be regarded to as a baseline for quantization-based data-hiding methods, is rigorously analyzed. An accurate procedure for computing the exact probability of bit error is given, as well as the optimal weights in a newly proposed decoding structure, for significant improvements on performance. The results are particularized for a JPEG compression scenario which allows to show their usefulness. Also a comparison between the mean square error and perceptual distorsion measurements is done. Experimental results validating the proposed theory are presented.

1. INTRODUCTION.

Although quantization-based methods have been presented since the beginnings of watermarking, it was not until very recently that the idea was revisited from a sound theoretical perspective in the form of a data hiding scheme known as Quantization Index Modulation (QIM) [1], which hides information by constructing a data-driven set of quantizers. This method was later connected to an old paper by Costa [2] to realize that by adding back a fraction of the quantization error, performance could be significantly improved. This scheme was thus termed Distortion Compensated QIM (DC-QIM).

The original proposal of DC-QIM can be adapted for using many off-the-shelf vector quantizers. In particular, a considerable attention has been paid to the special case called Dither Modulation (DM) [1] —or formally equivalent schemes [3], [4]—, which has the advantage of its simplicity. Here we consider a (binary) multidimensional extension of Distortion Compensated DM (DC-DM) which can be regarded as a baseline for more sophisticated QIM schemes [1].

Throughout the paper we will assume that the host image coefficients are arranged in a vector $\boldsymbol{x}$, so that the watermarked image can be written as $\boldsymbol{y} = \boldsymbol{x} + \boldsymbol{w}$, being $\boldsymbol{w}$ the watermark. The information to be hidden is represented by a vector $\boldsymbol{b}$ with N binary antipodal components, i.e., $b_j = \pm 1, j = 1, \cdots, N$. Following most existing schemes, we will consider that the $j-$th bit is hidden in a key-dependent set of coefficients $\mathcal{S}_j$ with cardinality L_j, for all $j = 1, \cdots, N$. The total set of coefficients devoted to data hiding is denoted by $\mathcal{S} \triangleq \bigcup_{i=1}^{N} \mathcal{S}_i$. For convenience, $\boldsymbol{w}_j$ stands for the vector comprising those samples with indices belonging to $\mathcal{S}_j$. We will also assume that prior to decoding the watermarked image is sent through an additive probabilistic noise channel, so that the image at its output $\boldsymbol{z}$ can be written as $\boldsymbol{z} = \boldsymbol{y} + \boldsymbol{n} = \boldsymbol{x} + \boldsymbol{w} + \boldsymbol{n}$, where $\boldsymbol{n}$ is the noise vector. By virtue of the pseudorandom choice of the indices in $\mathcal{S}$ we may assume that the samples in $\boldsymbol{n}$ are also mutually independent, with zero mean and variances $\sigma^2_{n_i}, i \in \mathcal{S}$.

To measure the impact of the attack, we will follow the popular *watermark-to-noise* ratio (WNR), defined as $\text{WNR} \triangleq 10\log_{10} \sum_{i\in\mathcal{S}} \text{E}\{w_i^2\} / \sum_{i\in\mathcal{S}} \sigma^2_{n_i}$. Since it is a MSE measure, it does not take into account the characteristics of the Human Visual System (HVS), so we will study also a perceptual distortion measurement, as that proposed in [5].

The paper is organized as follows: In Sect. 2, we will introduce the basic concepts of DC-DM whereas its performance analysis and numerical computation is studied in Sect. 3. Sect. 4 is devoted to JPEG compression and Sect. 5 to perceptual measurements. Finally, in Sect. 6 experimental results are presented and in Sect. 7 conclusions are expounded.

2. BASIC CONCEPTS OF DC-DM.

Structured quantization-based methods ([3], [1]) hide information by constructing a set of vector quantizers $\boldsymbol{Q}_{\boldsymbol{b}}(\cdot)$, each representing a different codeword $\boldsymbol{b}$. So, given a host vector $\boldsymbol{x}$ and an information codeword $\boldsymbol{b}$, the embedder constructs the watermarked vector $\boldsymbol{y}$ by simply quantizing $\boldsymbol{x}$ with $\boldsymbol{Q}_{\boldsymbol{b}}(\cdot)$, i.e. $\boldsymbol{y} = \boldsymbol{Q}_{\boldsymbol{b}}(\boldsymbol{x})$.

Here we will analyze the simplest (and most studied) implementation of these methods, the binary Distortion Compensated Dither Modulation (DC-DM) [1]. In the binary DC-DM the watermark samples in the set $\mathcal{S}_j, j = 1 \cdots, N$,

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are given by $\boldsymbol{w}_j = \nu_j \boldsymbol{e}_j$, i.e. the L-dimensional quantization error $\boldsymbol{e}_j \triangleq \boldsymbol{Q}_{b_j}(\boldsymbol{x}_j) - \boldsymbol{x}_j$, weighted by an optimizable distortion-compensating parameter ν_j, $0 < \nu_j \leq 1$. Then, we will have

$$\boldsymbol{y}_j = \boldsymbol{Q}_{b_j}(\boldsymbol{x}_j) - (1-\nu_j)\boldsymbol{e}_j, \;\; j = 1, \cdots, N \tag{1}$$

The uniform quantizers $\boldsymbol{Q}_{-1}(\cdot)$ and $\boldsymbol{Q}_{+1}(\cdot)$ are such that the corresponding centroids are the points in the lattices

$$\begin{aligned} \Lambda_{-1} &= 2(\Delta_1\mathbb{Z}, \cdots, \Delta_L\mathbb{Z})^T + \boldsymbol{d} \\ \Lambda_{+1} &= 2(\Delta_1\mathbb{Z}, \cdots, \Delta_L\mathbb{Z})^T + (\Delta_1, \cdots, \Delta_L)^T + \boldsymbol{d} \end{aligned} \tag{2}$$

with $\boldsymbol{d} \in \mathbb{R}^L$ a key-dependent dithering vector. Note that, in contrast to [1], our setup allows for different quantization steps to be used in each dimension to better account for perceptual constraints.

If the quantization step in each dimension is small enough, we can consider that the quantization error e_i in each dimension will be uniformly distributed between $[-\Delta_i, \Delta_i)$, being $2\Delta_i$ the quantization step. Thus, the embedding distortion in each dimension will be $\mathrm{E}\{w_i^2\} = \nu_j^2\Delta_i^2/3$.

Finally, decoding is implemented as

$$\begin{aligned} \hat{b}_j &= \arg\min_{-1,1} \left\{ \left(\boldsymbol{z}_j - \boldsymbol{Q}_{b_j}(\boldsymbol{z}_j)\right)^t \boldsymbol{B}_j \left(\boldsymbol{z}_j - \boldsymbol{Q}_{b_j}(\boldsymbol{z}_j)\right) \right\}, \\ & \quad j = 1, \cdots, N. \end{aligned} \tag{3}$$

where $\boldsymbol{B}_j = \mathrm{diag}(\beta_{j_1}/\Delta_{j_1}^2, \cdots, \beta_{j_L}/\Delta_{j_{L_j}}^2)$ and $\mathcal{S}_j = \{j_1, \cdots, j_{L_j}\}$. These weighting vectors $\boldsymbol{\beta}_j$ allow to improve decoding when additional information about the noise pdf is available, and are dealt with in Section 3. On the other hand, the normalization by Δ_i in the i-th dimension is reasonable if one thinks that noise variance will be roughly proportional to Δ_i^2 to reduce the perceptual impact of the attack. For simplicity, in the next section we will analyze the case in which no weights other than the normalization by Δ_i are used, that is, $\boldsymbol{\beta}_i = 1$. The analysis given here can be readily extended for an arbitrary weights vector.

3. PERFORMANCE ANALYSIS AND NUMERICAL COMPUTATION.

To analyze the performance of this scheme in terms of the bit error probability (P_e), we will define

$$\begin{aligned} u_i &\triangleq z_i - Q_{b_j}(z_i) \\ &= Q_{b_j}(x_i) - (1-\nu_j)e_i + n_j - Q_{b_j}(z_i) \\ &= 2l\Delta_i - (1-\nu_j)e_i + n_i \end{aligned} \tag{4}$$

for all $i \in \mathcal{S}$ and some integer l. Since u_i is a quantization error generated by a uniform quantizer of step size $2\Delta_i$, then u_i must belong to $[\Delta_i, \Delta_i)$, and l in (4) takes the appropriate value so that this is accomplished. Consequently, the pdf of u_i can be written as

$$\begin{aligned} & f_{u_i}(u_i) = \\ & \begin{cases} \sum_{l=-\infty}^{\infty} f_{u_i'}(u_i - 2l\Delta_i), & u_i \in [-\Delta_i, \Delta_i) \\ 0, & \text{otherwise} \end{cases} \end{aligned} \tag{5}$$

where $u_i' \triangleq n_i - (1-\nu_j)e_i$, is a random variable with pdf

$$f_{u_i'}(u_i') = f_{n_i}(u_i') * \frac{1}{(1-\nu_j)} f_{e_i}(u_i'/(1-\nu_j)) \tag{6}$$

The folding effect in (5) can be seen as a aliasing phenomenon, due to the periodicity of the lattices.

To follow a strategy similar to the one described in [6] and given (3) with $\boldsymbol{\beta}_i = 1$, we will define $\boldsymbol{v}$ as the vector with components $v_i \triangleq u_i/\Delta_i$, $i = 1, \cdots, L_j$, so we can write the bit error probability for the j-th hidden bit as

$$\begin{aligned} P_e(j) &= P\{\|\boldsymbol{v}_j'\|^2 > \|\boldsymbol{v}_j' - (1, \cdots, 1)^T\|^2\} \\ &= P\left\{ \sum_{i \in \mathcal{S}_j} v_i' > L_j/2 \right\}, \end{aligned} \tag{7}$$

where $\boldsymbol{v}'$ is an auxiliary random vector with independent components such that $\boldsymbol{v}' \triangleq |\boldsymbol{v}|$ with pdf

$$f_{v_i'}(v_i') \triangleq \begin{cases} \Delta_i[f_{u_i}(v_i'\Delta_i) + f_{u_i}(-v_i'\Delta_i)], & \text{if } 0 \leq v_i' \leq 1 \\ 0, & \text{otherwise} \end{cases} \tag{8}$$

If we define $r_j \triangleq \sum_{i \in \mathcal{S}_j} v_i'$, then the computation of $P_e(j)$ is equivalent to integrating the tail of the pdf of r_j from $L_j/2$, but since the v_i' are independent random variables, the pdf of r_j is just the convolution of the marginal pdf's of v_i', $i \in \mathcal{S}_j$. An efficient way to compute it is with the DFT method proposed in [7].

If the cardinality L_j of each subset $\mathcal{S}_j$ is large enough and under some additional conditions discussed in [6], it is possible to resort to the Central Limit Theorem (CLT), to write that

$$P_e(j) \approx \mathcal{Q}\left(\frac{\frac{1}{2}\sum_{k \in \mathcal{S}_j} \beta_k - \sum_{k \in \mathcal{S}_j} \beta_k \mathrm{E}\{v_k'\}}{\sqrt{\sum_{k \in \mathcal{S}_j} \beta_k^2 \mathrm{Var}\{v_k'\}}} \right) \tag{9}$$

where $\mathcal{Q}(x) \triangleq \frac{1}{\sqrt{2\pi}} \int_x^\infty e^{-\frac{\tau^2}{2}} d\tau$.

In [7] the optimal values for the decoding weights β_i were also introduced

$$\beta_i^* = K \cdot \frac{\left(\frac{1}{2} - \mathrm{E}\{v_i'\}\right)}{\mathrm{Var}\{v_i'\}} \tag{10}$$

where K is an irrelevant positive real constant, since $\boldsymbol{\beta}^*$ can be scaled without any impact on performance. Also, it is

very interesting to note that some of the β_i^* may be negative. This will happen when the random variable v_i' is such that $\mathrm{E}\{v_i'\} > 1/2$, which may occur for large distortions.

Finally, as it can be inferred from (10), in order to compute the optimal decoding weights, knowledge of $\mathrm{E}\{v_i'\}$ and $\mathrm{Var}\{v_i'\}$ is required. Note that due to the aliasing and truncation effects that show up in the construction of $\boldsymbol{v}'$, this information is not directly derivable from the first and second order moments of the noise random variable.

4. JPEG COMPRESSION.

In the previous development we have assumed that the noise $\boldsymbol{n}$ is independent of $\boldsymbol{x}$. This is clearly not the case if the attack is a coarse quantization, like the popular JPEG compression, which is supposed to be one of the most likely unintentional attacks. In this section we develop a method for estimating P_e for a given quality factor.

Assuming the bits to transmit are equiprobable, and due to the symmetry of the JPEG compression, we will concentrate in the case when $b = -1$, without loss of generality. Given a JPEG quantization step δ_i corresponding to the i-th dimension, we are interested in computing the probability associated to each JPEG centroid, noting that this probability will depend not only on the pdf of the host image (here assumed to be Laplacian with parameter λ) but also on that of the watermark. To that end, we have to determine the limits of each quantization bin; the DC-DM centroid associated to the k-th JPEG bin with limits $a_{i_k}^{\pm} = k\delta_i \pm \delta_i/2$ (the upper or lower limit, depending of the sign, in the i-th dimension) is

$$Q_{-1}(a_{i_k}^{\pm}) = d_i + 2\Delta_i \cdot \mathrm{round}\left(\frac{a_{i_k}^{\pm} - d_i}{2\Delta_i}\right) \qquad (11)$$

so the offset between the JPEG centroid and the DC-DM centroid is $e_y(a_{i_k}^{\pm}) \triangleq a_{i_k}^{\pm} - Q_{-1}(a_{i_k}^{\pm})$. This offset corresponds to the watermarked image and it can be shown to map back into the host image as

$$e_x(a_{i_k}^{\pm}) \quad = \quad \frac{\min\{\max[e_y(a_{i_k}^{\pm}), -(1-\nu_j)\Delta_i], (1-\nu_j)\Delta_i\}}{(1-\nu_j)},$$

for all $i \in \mathcal{S}_j$, $j = 1, \cdots, N$. Therefore, if we define $\gamma_{j_k}^{\pm} \triangleq Q(a_{j_k}^{\pm}) + e_x(a_{j_k}^{\pm})$, we can see that it corresponds to the upper (lower) limit of the JPEG quantization bin for the k-th JPEG centroid in the i-th dimension of the host image. Now we can compute the probability of occurrence for this centroid as

$$P_{i_k} = P(x_i \leq \gamma_{i_k}^{+}) - P(x_i \leq \gamma_{i_k}^{-}) \qquad (12)$$

with

$$P(x_i \leq \tau) = \begin{cases} \frac{1}{2}e^{\lambda_i \tau}, & \text{if } \tau \leq 0 \\ 1 - \frac{1}{2}e^{-\lambda_i \tau}, & \text{if } \tau > 0 \end{cases} \qquad (13)$$

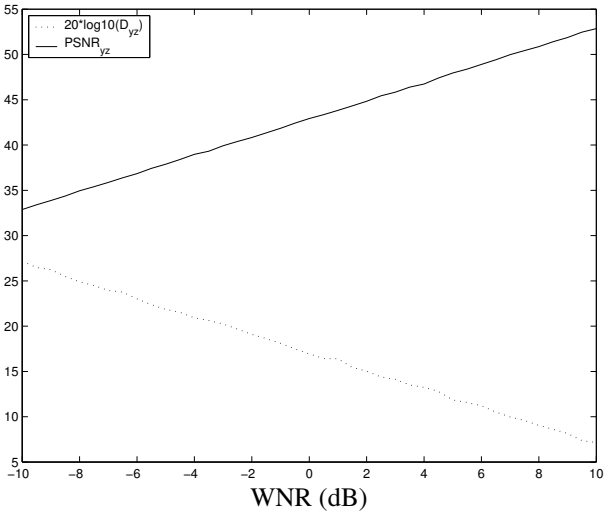

Fig. 1. Watson's perceptual distortion (D_{yz}) and $PSNR_{yz}$ versus WNR for DC-DM ($L = 10$ and $\nu = 0.5$) with uniform noise.

The parameter λ_j for the Laplacian distribution can be estimated using the maximum likelihood criterion.

Notice that P_{i_k} plays the same role as $f_{u_i'}$ in 5. Once we know the probability of a representative set of JPEG centroids, it is necessary to "fold" them onto the interval $[-\Delta_i, \Delta_i)$ as in (5), and then follow a similar strategy to that developed in the previous section to compute $P_e(j)$ by convolving the pdf's of the JPEG centroids in each dimension. In our practical implementation we have used the DFT method introduced in [7].

5. PERCEPTUAL MEASUREMENTS.

Although measurements based on square error are widely used, there is also a large number of authors who have criticized it and have claimed the use of a perceptually-based measurement (see e.g. [8], [9] or [10]).

In this section we provide a comparison between the WNR, the Peak Signal to Noise Ratio ($PSNR$) and the perceptual measurement defined by Watson in [5], which is related to Ahumada's ideas in [11]. With this objective, we have watermarked *Lena* with size 256×256 and compared the WNR with D_{yz} and $PSNR_{yz}$, i.e. Watson's distortion measure between $\boldsymbol{y}$ and $\boldsymbol{z}$ and the PSNR, respectively. Since the embedding method is always the same, we are interested in comparing the distortion that the attacker is introducing, by using different measurements. In this case we have varied the WNR from -10dB to $+10$dB, with $L = 10$, $\nu = 0.5$ and uniform noise proportional in each coefficient to the corresponding JPEG quantization step for a Quality Factor of 80. Applying Parseval's Theorem to the bidimensional DCT, it can be shown that the power of the attack in the DCT domain, where the WNR is measured, is is iden-

tical to that in the spatial domain, where $PSNR_{yz}$ is computed, so it follows that the relationship between the WNR and the $PSNR_{yz}$ is linear. Nevertheless the relation between the WNR and D_{yz} is quite involved. First of all, let us define:

$$d_{ijk} \triangleq e_{ijk}/m_{ijk} \tag{14}$$

where e_{ijk} is the difference between $\boldsymbol{y}$ and $\boldsymbol{z}$ in the ij-th frequency for the k-th block and m_{ijk} is the masked threshold for that coefficient. If e_{ijk} is a random variable whose variance is proportional to $D_c \triangleq \sum_{k\in\mathcal{S}}\sigma^2_{n_k}$, since m_{ijk} does not depend on D_c, we can define certain r_{ijk} invariant with D_c, in such a way that

$$d_{ijk} = \sqrt{D_c} r_{ijk} \tag{15}$$

so, following Watson the spatial error pooling will be computed as,

$$p_{ij} = \left(\sum_{k=1}^{B} |d_{ijk}|^{\beta_s}\right)^{1/\beta_s} = \left(\sum_{k=1}^{B} |\sqrt{D_c} r_{ijk}|^{\beta_s}\right)^{1/\beta_s} \tag{16}$$

being B the number of 8×8 blocks.[1] Therefore,

$$\log_{10} p_{ij} = \frac{1}{2}\log_{10}(D_c) + \frac{1}{\beta_s}\log_{10}\left(\sum_{k=1}^{B} |r_{ijk}|^{\beta_s}\right) \tag{17}$$

For the parameters proposed in [5] $D_{yz} = \max_{ij} p_{ij}$, so $20\cdot\log_{10}(D_{yz})$ will be proportional to WNR, as can be seen in Fig. 1. Also from (17) we can see that this curve will be shifted depending on the p.d.f. of the noise and the relative variances among its coefficients. Thus, we can think of computing the largest modification of the host signal that is constrained to yield a given perceptual distortion. Applying Lagrange's multipliers we can write:

$$\varphi_{ij}(e_{ijk}) = \sum_{k=1}^{B} e^2_{ijk} - \lambda\left[\sum_{k=1}^{B}\frac{e^4_{ijk}}{m^4_{ijk}} - K\right] \tag{18}$$

where the rightmost sum represents the perceptual distortion for the ij-frequency. So (18) yields ${e^2_{ijk}}^* = K_{ij} m^4_{ijk}$, with K_{ij} a proper constant. A similar development could be done for the distortion due to the embedding process. So this formula will be useful also for computing the watermark with the largest variance constrained to produce a given perceptual distortion.

6. EXPERIMENTAL RESULTS.

In order to validate the analytical results presented heretofore, we have watermarked the image *Lena* with size 256×256 in the DCT domain taking into account the perceptual thresholds described in [11] and we have represented the BER vs. WNR curves for different noise distributions and decoders. First of all (Fig. 2), we have studied additive noise attacks, with both uniform and Gaussian distributions, and with variances which depend for each DCT coefficient on the corresponding squared quantization step used in JPEG compression with a quality factor (QF) of 85. The resulting noise is scaled in order to work with different WNR operating points. The theoretical curves for the uniform case correspond to using (9), while for Gaussian noise the DFT technique explained in Sect. 3 was employed. Fig. 2 also plots the upper bound previously published in [6]. For the uniform case, Fig. 2 clearly shows the improvement on performance that results when the optimal decoding weights in (10) are used. The slight difference between empirical and theoretical results is due to the non-uniformity of the image within the quantization step. This also explains why that difference is larger when the WNR increases.

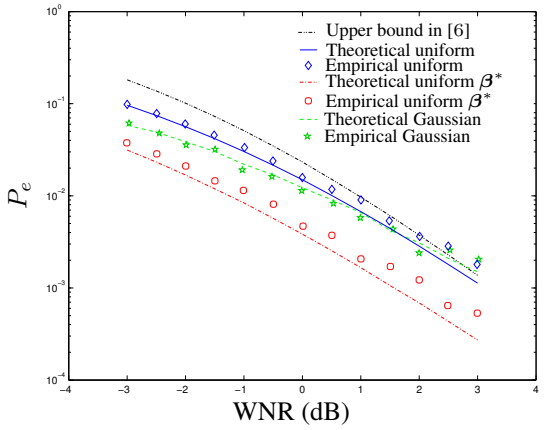

Fig. 2. BER versus WNR for DC-DM ($L = 10$ and $\nu = 0.5$) with additive noise proportional to JPEG with QF = 85.

In Fig. 3 we depict the BER vs. WNR when the same image is compressed with QF's ranging from 60 to 90, comparing the empirical results with the analytical ones obtained by following the procedure described in 4. The results obtained show that binary DC-DM performance are very accurately predicted by our theory.

7. CONCLUSIONS

In this paper we have presented a theoretical analysis for the binary DC-DM data hiding method, which can be considered as a reference for other more sophisticated quantization-based schemes. An accurate analysis was lacking in the data hiding literature and only rough upper bounds were available.

The procedure here given not only allows to assess be-

[1] For a full comprehension of these expressions, the reader is refered to Watson and Ahumada's papers ([5]-[11]).

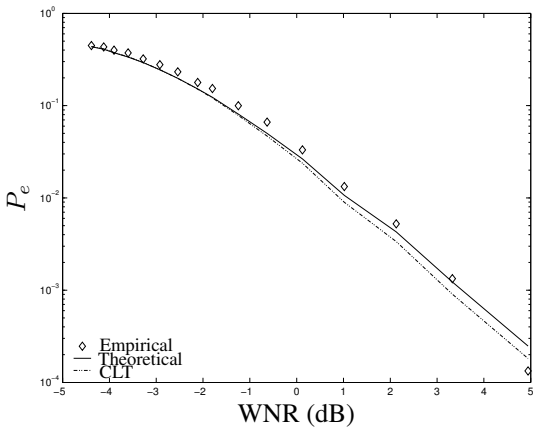

Fig. 3. BER versus WNR for DC-DM ($L = 10$ and $\nu = 0.5$) with JPEG compression with QF between 60 and 90.

forehand the bit error rate performance of the DC-DM method, but to improve the detector by exploiting any available knowledge about the noise joint pdf. JPEG case has been treated here in some detail.

Finally, we have claimed the use of perceptual distortion measures replacing typical squared error measures which do not take into account the HVS' characteristics.

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